

Option Pricing, Hedging, and Efficient Monte Carlo Methods

Chuan-Hsiang Han

Dept. of Quantitative Finance, NTHU

Institute of Statistics
Academia Sinica

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Black-Scholes Model

Under the **physical** probability space $(\Omega, \mathcal{F}, \mathcal{F}_t, \mathbb{P})$, there are two assets within an economy:

$$dS_t = \mu S_t dt + \sigma S_t dW_t, \text{ (stock)}$$

$$dr_t = r dt. \text{ (bond)}$$

- μ : rate of returns.
- r : risk-free interest rate.
- σ : volatility (**constant**).
- W_t : 1-d. standard Brownian Motion.

Black-Scholes Theory

The European option price is

$$P(t, S_t) = \mathbb{E}^* \left\{ e^{-r(T-t)} H(S_T) | \mathcal{F}_t \right\}$$

defined on the risk-neutral **pricing** probability space $(\Omega, \mathcal{F}, \mathcal{F}_t, \mathbb{P}^*)$ such that

$$dS_t = r S_t dt + \sigma S_t dW_t^*.$$

Perfect replication of the discounted payoff:

$$P(0, S_0) = e^{-rT} H(S_T) - \int_0^T e^{-rs} \underbrace{\frac{\partial P}{\partial x}(s, S_s)}_{Delta} \sigma S_s dW_s^*.$$

Black-Scholes Formula

Typical payoff functions are nonlinear like

$$H(x) = \max\{x - K, 0\} = (x - K)^+ \text{ a **call** .}$$

$$H(x) = \max\{K - x, 0\} = (K - x)^+ \text{ a **put** .}$$

K is the **strike** price.

The celebrated BS formula for the **Euro-pean** call option price is

$$P(t, S_t = x) = x\mathcal{N}(d_1) - Ke^{-r(T-t)}\mathcal{N}(d_2),$$

$$\text{where } d_1 = \frac{\ln(x/K) + (r + \frac{1}{2}\sigma^2)(T-t)}{\sigma\sqrt{T-t}} \text{ and } d_2 = d_1 - \sigma\sqrt{T-t}.$$

Some Empirical Evidence

- (1) S. Alizadeh, M. Brandt, and F. Diebold, “Range-based estimation of stochastic volatility models,” *Journal of Finance*, 57, 1047-1091, 2002.
- (2) M. Chernov, R. Gallant, E. Ghysels, and G. Tauchen, “Alternative models for stock price dynamics,” *Journal of Econometrics*, 2003, vol. 116, issue 1-2, pages 225-257.
- (3) ...

Recast Financial Problems

Under generalized models,

- Pricing: No closed-form solution.

$$P_t = \mathbb{E}^* \left\{ e^{-r(T-t)} H(S_T) | \mathcal{F}_t \right\}.$$

Monte Carlo is a good computational *option*.

- Hedging: No perfect (self-financing) replication.

Is Delta hedge enough? What Delta?

Multifactor Stochastic Volatility Model

Under a risk-neutral prob. meas. $\mathbb{P}^{*(\Lambda)}$, a multifactor SV model is of the form:

$$dS_t = rS_t dt + f(Y_t, Z_t)S_t dW_t^{(0)*},$$

$$dY_t = c_1(Y_t, Z_t)dt + g_1(Y_t, Z_t)dW_t^{(1)*},$$

$$dZ_t = c_2(Y_t, Z_t)dt + g_2(Y_t, Z_t)dW_t^{(2)*}$$

$$d\langle W^{(0)}, W^{(1)} \rangle_t = \rho_1 dt$$

$$d\langle W^{(0)}, W^{(2)} \rangle_t = \rho_2 dt$$

$$d\langle W^{(1)}, W^{(2)} \rangle_t = \rho_{12} dt.$$

Martingale Representation

Risky asset dynamics:

$$dS_t = rS_t dt + \sigma_t S_t dW_t^*,$$

σ_t is a diffusion process.

$P(0, S_0, \sigma_0) = e^{-rT} H(S_T) - \mathcal{M}(P) + \text{Martingales}$
with $\mathcal{M}(P) = \int_0^T e^{-rs} \frac{\partial P}{\partial x}(s, S_s, \sigma_s) \sigma_s S_s dW_s^*$ is
a zero-centered martingale.

Additional *martingales* are related to non-tradable risks and perhaps difficult to compute.

Monte Carlo Pricing with Control Variate

$$P(0, S_0, \sigma_0) \approx \frac{1}{N} \sum_{i=1}^N \left[e^{-rT} H(S_T^{(i)}) - \mathcal{M}^{(i)}(\tilde{P}) \right],$$

where $\mathcal{M}(\tilde{P}) = \int_0^T e^{-rs} \frac{\partial \tilde{P}}{\partial x}(s, S_s, \sigma_s) \sigma_s S_s dW_s^*$ is a *martingale* with \tilde{P} being an approximation of P .

Control by Hedging Portfolio

Clelow and Carverhill* used hedging portfolio as a control s.t.

$$P(0, S_0, \sigma_0) \approx \frac{1}{N} \sum_{i=1}^N \left[e^{-rT} H(S_T^{(i)}) - \mathcal{M}^{(i)}(P_{BS}) \right],$$

with $P_{BS}(t, S_t) = P_{BS}(t, S_t; \hat{\sigma})$. The choice of $\hat{\sigma}$ depends on the **long-run mean** of the driving volatility process.

*Clelow, L. and Carverhill, A. (1994) On the simulation of contingent claims, Journal of Derivatives 2:66-74.

Diffusion Operator Integral Method

Heath and Platen* proposed to use the option price approximated from **deterministic** volatility by removing its random source.

*Heath, D. and Platen, E. (2002) A variance reduction technique based on integral representations, *Quantitative Finance* 2:362-369.

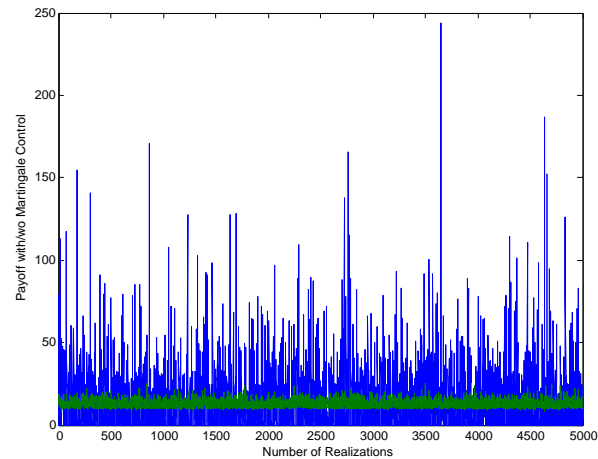
Homogenization Method

Fouque and H.* use the **homogenized** option price $P_{BS}(t, S_t; \bar{\sigma})$ to construct a martingale control $\mathcal{M}^{(i)}(P_{BS})$.

The **effective** variance $\bar{\sigma}^2$ is defined as the averaging of the variance function w.r.t. an **invariant** distribution of a volatility process.

*Fouque, J.P. and Han (2004) A control variate method to evaluate option prices under multi-factor stochastic volatility models. Submitted.

Evaluate European Option by Martingale Control Variate



blue: Basic MC samples

green: MC+CV samples

A Variance Problem

A martingale control Variate method ends up to compute

$$P(0, S_0, Y_0, Z_0) \approx \frac{1}{N} \sum_{i=1}^N \left[e^{-rT} H(S_T^{(i)}) - \mathcal{M}^{(i)}(\tilde{P}) \right],$$

where the *martingale* is defined by

$$\mathcal{M}(\tilde{P}) = \int_0^T e^{-rs} \frac{\partial \tilde{P}}{\partial x}(s, S_s, Y_s, Z_s) \sigma_s S_s dW_s^*$$

with \tilde{P} being an approx. to P .

Q: Can we estimate $Var(e^{-rT} H(S_T) - \mathcal{M}(\tilde{P}))$?

Time-Scaled Stochastic Volatility model

$$dS_t = rS_t dt + \sigma_t S_t dW_{0t}^*$$

$$\sigma_t = f(Y_t, Z_t)$$

$$dY_t = \left[\frac{1}{\varepsilon} c_1(Y_t) + \frac{g_1(Y_t)}{\sqrt{\varepsilon}} \Lambda_1(Y_t, Z_t) \right] dt$$

$$+ \frac{g_1(Y_t)}{\sqrt{\varepsilon}} \left(\rho_1 dW_{0t}^* + \sqrt{1 - \rho_1^2} dW_{1t}^* \right)$$

$$dZ_t = \left[\delta c_2(Z_t) + \sqrt{\delta} g_2(Z_t) \Lambda_2(Y_t, Z_t) \right] dt + \sqrt{\delta} g_2(Z_t) \\ \cdot \left(\rho_2 dW_{0t}^* + \rho_{12} dW_{1t}^* + \sqrt{1 - \rho_2^2 - \rho_{12}^2} dW_{2t}^* \right)$$

A European option price is defined by

$$P^{\varepsilon, \delta}(t, x, y, z) = \mathbb{E}^*_{t, x, y, z} \left\{ e^{-r(T-t)} H(S_T) \right\}.$$

Variance Decomposition

Case: No Correlation between BMs

$$\begin{aligned}
 \text{Var} \left(e^{-rT} H(S_T) - \mathcal{M}(P_{BS}) \right) &= \mathbb{E}^*_{0,x,y,z} \left\{ \right. \\
 &\int_0^T e^{-2rs} \left(\frac{\partial P^{\varepsilon,\delta}}{\partial x} - \frac{\partial P_{BS}}{\partial x} \right)^2 (s, S_s, Y_s, Z_s) f^2(Y_s, Z_s) S_s^2 ds \\
 &+ \frac{1}{\varepsilon} \int_0^T e^{-2rs} \left(\frac{\partial P^{\varepsilon,\delta}}{\partial y} \right)^2 (s, S_s, Y_s, Z_s) g_1^2(Y_s) ds \\
 &\left. + \delta \int_0^T e^{-2rs} \left(\frac{\partial P^{\varepsilon,\delta}}{\partial z} \right)^2 (s, S_s, Y_s, Z_s) g_2^2(Z_s) ds \right\}.
 \end{aligned}$$

Variance Analysis

Under some smooth and bound conditions,

$$1. \mathbf{E}^* \left\{ \int_0^T e^{-2rs} \left(\frac{\partial P^{\varepsilon, \delta}}{\partial x} - \frac{\partial P_{BS}}{\partial x} \right)^2 f^2(Y_s, Z_s) S_s^2 ds \right\} < C \max\{\varepsilon, \delta\}$$

$$2. \mathbf{E}^* \left\{ \int_0^T e^{-2rs} \left(\frac{\partial P^{\varepsilon, \delta}}{\partial y} \right)^2 g_1^2(Y_s) ds \right\} \leq C \varepsilon^2$$

$$3. \mathbf{E}^* \left\{ \int_0^T e^{-2rs} \left(\frac{\partial P^{\varepsilon, \delta}}{\partial z} \right)^2 g_2^2(Z_s) ds \right\} \leq C$$

such that

$$\text{Var} \left(e^{-rT} H(S_T) - \mathcal{M}(P_{BS}) \right) \leq C \max\{\varepsilon, \delta\}.$$

First Inequality

By Cauchy-Schwartz inequality

$$\begin{aligned} & \mathbb{E}^* \left\{ \int_0^T e^{-2rs} \left(\frac{\partial P^{\varepsilon, \delta}}{\partial x} - \frac{\partial P_{BS}}{\partial x} \right)^2 f^2(Y_s, Z_s) S_s^2 ds \right\} \\ & \leq \sqrt{\mathbb{E}^* \left\{ \int_0^T (e^{-rs} S_s)^4 f^4(Y_s, Z_s) ds \right\}} \\ & \quad \times \sqrt{\mathbb{E}^* \left\{ \int_0^T \left(\frac{\partial P^{\varepsilon, \delta}}{\partial x} - \frac{\partial P_{BS}}{\partial x} \right)^4 ds \right\}} \end{aligned}$$

Delta Approximation

$$\begin{aligned}\frac{\partial P^{\varepsilon, \delta}}{\partial S_t}(t, S_t, Y_t, Z_t) &= \mathbb{E}^*_t \left\{ e^{-r(T-t)} \mathbf{I}_{\{S_T > K\}} \frac{\partial S_T}{\partial S_t} \right\} \\ &= \tilde{E}_t \left\{ \mathbf{I}_{\{S_T > K\}} \right\}\end{aligned}$$

where the Radon-Nikodym derivative is

$$\frac{d\tilde{P}}{d\mathbb{P}^*} = e^{-\int_0^T \frac{\sigma_t^2}{2} dt + \int_0^T \sigma_t dW_t^{(0)*}}.$$

Digital option approximation yields

$$\left| \left(\frac{\partial P^{\varepsilon, \delta}}{\partial x} - \frac{\partial P_{BS}}{\partial x} \right) (t, S_t, Y_t, Z_t) \right| \leq C \max\{\sqrt{\varepsilon}, \sqrt{\delta}\}.$$

Second Inequality

$$\int_0^T e^{-2rs} \left(\frac{\partial P^{\varepsilon, \delta}}{\partial y} \right)^2 (s, S_s, Y_s, Z_s) g_1^2(Y_s) ds \leq C \varepsilon^2.$$

Conditional on the volatility process,

$$P^{\varepsilon, \delta}(t, x, y, z) = \mathbb{E}^*_t \left\{ P_{BS} \left(t, x; K, T; \sqrt{\bar{\sigma}_{av}^2} \right) \right\},$$

where the realized variance is denoted by $\bar{\sigma}_{av}^2$:

$$\bar{\sigma}_{av}^2(y, z) = \frac{1}{T-t} \int_t^T f(Y_s, Z_s)^2 ds.$$

Chain Rules

$$\frac{\partial P^{\varepsilon, \delta}}{\partial y} = \mathbb{E}^*_t \left\{ \frac{\partial P_{BS}}{\partial \sigma} \left(t, x; K, T; \sqrt{\bar{\sigma}_{av}^2(y, z)} \right) \frac{\partial \sqrt{\bar{\sigma}_{av}^2}}{\partial y} \right\}.$$

$$\frac{\partial \sqrt{\bar{\sigma}_{av}^2}}{\partial y} = \frac{\int_t^T \left[\frac{\partial f}{\partial y}(Y_s, Z_s) \frac{\partial Y_s}{\partial y} + \frac{\partial f}{\partial z}(Y_s, Z_s) \frac{\partial Z_s}{\partial y} \right] f(Y_s, Z_s) ds}{(T - t) \sqrt{\bar{\sigma}_{av}^2}}.$$

How fast does $\left(\frac{\partial Y_s}{\partial y} \quad \frac{\partial Z_s}{\partial y} \right)$ grow?

Perturbed Dynamical System

Rescaling $\tilde{Y}_s^\varepsilon = Y_{s\varepsilon}$ and $\tilde{Z}_s^\varepsilon = Z_{s\varepsilon}$, we deduce

$$\begin{aligned} \frac{d}{ds} \begin{pmatrix} \frac{\partial \tilde{Y}_s^\varepsilon}{\partial y} \\ \frac{\partial \tilde{Z}_s^\varepsilon}{\partial y} \end{pmatrix} &= \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} \frac{\partial \tilde{Y}_s^\varepsilon}{\partial y} \\ \frac{\partial \tilde{Z}_s^\varepsilon}{\partial y} \end{pmatrix} \\ + \sqrt{\varepsilon} \cdot \begin{pmatrix} \nu_1 \sqrt{2} \frac{\partial \tilde{\Lambda}_1}{\partial y}(\tilde{Y}_s^\varepsilon, \tilde{Z}_s^\varepsilon) & \frac{\partial \tilde{\Lambda}_1}{\partial z}(\tilde{Y}_s^\varepsilon, \tilde{Z}_s^\varepsilon) \\ \sqrt{\delta} \nu_2 \frac{\partial \tilde{\Lambda}_2}{\partial y}(\tilde{Y}_s^\varepsilon, \tilde{Z}_s^\varepsilon) & -\delta + \sqrt{\delta} \nu_2 \sqrt{2} \frac{\partial \tilde{\Lambda}_2}{\partial z}(\tilde{Y}_s^\varepsilon, \tilde{Z}_s^\varepsilon) \end{pmatrix} \\ \cdot \begin{pmatrix} \frac{\partial \tilde{Y}_s^\varepsilon}{\partial y} \\ \frac{\partial \tilde{Z}_s^\varepsilon}{\partial y} \end{pmatrix} &\text{ with } \begin{pmatrix} \frac{\partial \tilde{Y}_0^\varepsilon}{\partial y} & \frac{\partial \tilde{Z}_0^\varepsilon}{\partial y} \end{pmatrix}^T = (1, 0)^T. \end{aligned}$$

Stability Theory

By a classical stability result,* we obtain $|\frac{\partial Y_s}{\partial y}| < C_1 e^{-(s-t)/\varepsilon}$ and $|\frac{\partial Z_s}{\partial y}| < C_2 \delta$ for some constants C_1 and C_2 .

*R. Bellman, Stability Theory of Differential Equations, McGraw-Hill, 1953.

Third Inequality

$$\int_0^T e^{-2rs} \left(\frac{\partial P^{\varepsilon, \delta}}{\partial z} \right)^2 (s, S_s, Y_s, Z_s) g_2^2(Z_s) ds \leq C$$

The proof is similar as in the second inequality.

Replication Error and Variance Reduction *

1. European Options
2. Barrier Options
3. American Options

*Fouque, J.-P. and H. (2005) A martingale control variate method for option pricing with stochastic volatility.

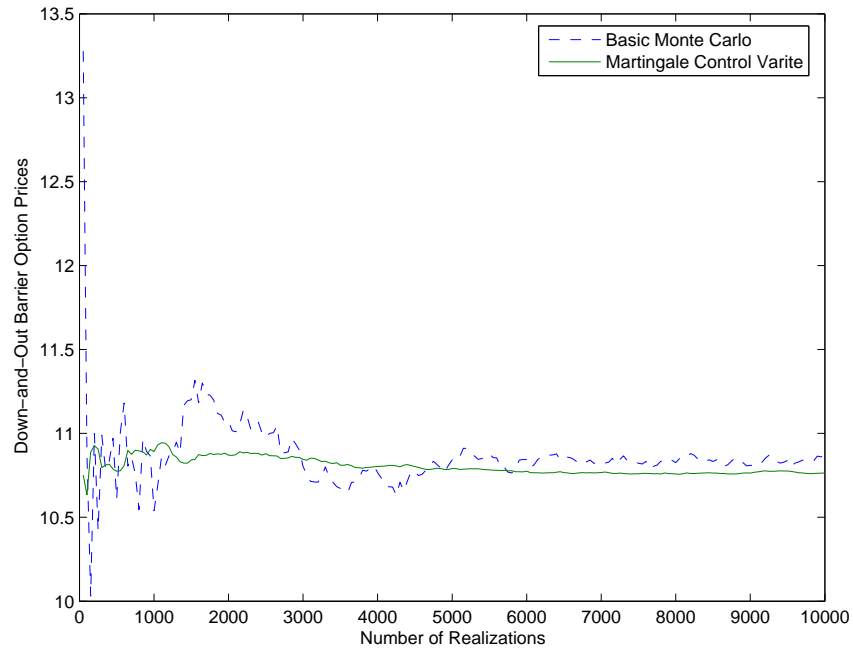
Numerical Results I: European Options
Double Heston Model

$1/\varepsilon$	δ	Std^{BMC}	Std^{MCV}	Ratio
1/75	0.01	0.1103 (7.03)	0.0068 (7.09)	265
1/50	0.1	0.1102 (6.97)	0.0073 (7.08)	230
1/10	0.5	0.1085 (6.94)	0.0103 (7.03)	111
1/5	1	0.1063 (6.91)	0.0113 (6.99)	89

Numerical Results II: Barrier Options

$1/\varepsilon$	δ	Std^{BMC}	Std^{MCV}	Ratio
100	0.01	0.2822 (10.82)	0.0304 (10.85)	86
75	0.1	0.2047 (10.77)	0.0306 (10.76)	45
50	1	0.2455 (11.21)	0.0474 (11.10)	27
25	10	0.2604 (12.62)	0.0417 (12.44)	39

Variance Reduction: a down and out Barrier Option



American Option Pricing Problem

Given the risk-neutral prob. space $(\Omega, \mathcal{F}, \mathbb{P}^*, \mathcal{F}_{[0:T]})$, an American option pricing problem is formulated as an **optimal stopping problem**:

$$P_{am}(0, S_0) = \sup_{0 \leq \tau \leq T} \mathbb{E}^* \left\{ e^{-r\tau} H(S_\tau) | \mathcal{F}_0 \right\},$$

where τ is any \mathcal{F}_t -adapted stopping time and S is the underlying asset price (diffusion) process.

Variational Inequality Characterization

It can be shown that $P_{am}(t, x)$ admits the classical solution of the **PDIE**

$$\begin{cases} \left(\frac{\partial}{\partial t} + \mathcal{A}_{\mathcal{S}} \right) P_{am}(t, x) \leq 0 \\ P_{am}(t, x) \geq H(x) \\ \left(\left(\frac{\partial}{\partial t} + \mathcal{A}_{\mathcal{S}} \right) P_{am}(t, x) \right) (P_{am}(t, x) - H(x)) = 0. \end{cases}$$

Or one can solve a **free boundary problem** in PDE.

Deterministic schemes are highly sensitive to dimensionalities.

Recent Development on Efficient Monte Carlo Pricing Algorithms

(1) **Primal Approach**: approximate optimal stopping rule

Tsitsiklis and Van Roy (2001), Longstaff and Schwartz (2001)

(2) **Dual Approach**: approximate (super-)martingales
Rogers (2002) used martingale approxim..

Haugh and Kogan (2004) used super-martingale approxim..

Primal Approach (I)

A Low-Biased Solution

For any stopping time $\tilde{\tau}$, a lower solution is deduced

$$\begin{aligned} P_{am}(0, S_0) &= \sup_{0 \leq \tau \leq T} \mathbb{E}^* \left\{ e^{-r\tau} H(S_\tau) | \mathcal{F}_0 \right\}, \\ &\geq \mathbb{E}^* \left\{ e^{-r\tilde{\tau}} H(S_{\tilde{\tau}}) | \mathcal{F}_0 \right\} \equiv P_{am}^{low}(0, S_0) \end{aligned}$$

$\tilde{\tau}$ can be estimated from least squares methods from the dynamic programming formulation.

Primal Approach (II)

Variance Reduction

By martingale control variate methods*,

$$\mathbb{E}^* \left\{ e^{-r\tilde{\tau}} H(S_{\tilde{\tau}}) \right\} = \mathbb{E}^* \left\{ e^{-r\tilde{\tau}} H(S_{\tilde{\tau}}) - \mathcal{M}_{\tilde{\tau}} \right\},$$

where $\mathcal{M}_{\tilde{\tau}} = \int_0^{\tilde{\tau}} e^{-rs} \frac{\partial \tilde{P}}{\partial x}(s, S_s) \sigma_s S_s dW_s$, and \tilde{P} is an approxim. of the option price, one can reduce the variance of the basic Monte Carlo estimator.

Given $\tilde{\tau}$, we transform an American option problem to a **Barrier option problem**.

*Fouque and H. (2006)

Dual Approach (I)

A Direct Monte Carlo Simulation

Rogers (2002) derived the duality of the American option problem by

$$P_{am}(0, S_0) = \inf_{\mathcal{M} \in H_0^1} \mathbb{E}^* \left\{ \sup_{0 \leq t \leq T} \left(e^{-rt} H(S_t) - \mathcal{M}_t \right) \right\},$$

$H_0^1 = \{ \text{all integrable martingales but vanish at time } 0 \}$

proof:

\geq : trivial

\leq : use Doob-Meyer decomposition of a supermartingale. (infimum can be attained)

Dual Approach (II)

A High-Biased Solution

Given any martingale $\tilde{M} \in H_0^1$, one deduces an upper solution

$$\begin{aligned} P_{am}^{high}(0, S_0) &\equiv \mathbf{E}^* \left\{ \sup_{0 \leq t \leq T} \left(e^{-rt} H(S_t) - \tilde{M}_t \right) \right\} \\ &\geq P_{am}(0, S_0) \end{aligned}$$

Given \tilde{M} we transform an American option problem to a **Lookback option problem**.

Dual Approach (III)

Error Bound Estimate

Lemma 1: For any given martingale $\tilde{M} \in H_0^1$, $P_{am}^{high}(0, S_0) \leq P_{am}(0, S_0) + \mathbb{E}^* \left\{ \left| M_T^* - \tilde{M}_T \right| \right\}$.

Proof:

$$\begin{aligned} & P_{am}^{high}(0, S_0) \\ &= \mathbb{E}^* \left\{ \sup_{0 \leq t \leq T} \left(e^{-rt} H(S_t) - M_t^* + M_t^* - \tilde{M}_t \right) \right\} \\ &\leq P_{am}(0, S_0) + \mathbb{E}^* \left\{ \sup_{0 \leq t \leq T} \left(M_t^* - \tilde{M}_t \right) \right\} \\ &\leq P_{am}(0, S_0) + \sqrt{\text{Var} \left\{ M_T^* - \tilde{M}_T \right\}} \end{aligned}$$

Variance Bound V.S. Error Bound

Lemma 2: For **low-biased solution**, the variance of its MCV estimator is

$$\begin{aligned} \text{Var} (H(S_{\underline{\tau}}) - \mathcal{M}(\underline{P}; \underline{\tau})) &= \text{Var} (\mathcal{M}(\mathcal{P} - \underline{P})) \\ &= E \left(\int_0^{\underline{\tau}} e^{-2rs} \left(\frac{\partial P_{am}}{\partial x} - \frac{\partial \underline{P}}{\partial x} \right) \sigma_s^2 S_s^2 ds \right) \\ &\leq E \left(\int_0^T e^{-2rs} \left(\frac{\partial P_{am}}{\partial x} - \frac{\partial \underline{P}}{\partial x} \right) \sigma_s^2 S_s^2 ds \right) \equiv VB \end{aligned}$$

For **high-biased solution**, the error bound was shown

$$P_{am}^{high}(0, S_0) - P_{am}(0, S_0) \leq \sqrt{VB}.$$

Remark: the STD of lower solution and the error bound of higher solution are bounded from above by the same quantity.

Numerical Results III: Low-Biased Solution

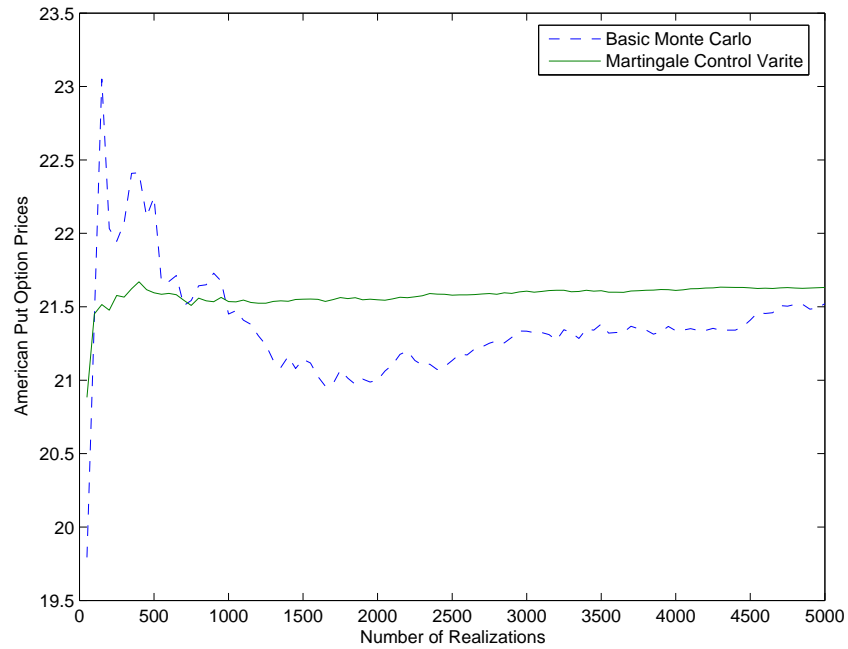
Primal Approach

Use the Least-squares method, which provides a biased **lower** bound solution.

$1/\varepsilon$	δ	Std_{low}^{PriMC}	$Std_{low}^{PriCV}(P_{BAW})$	Ratio
100	0.01	0.235 (21.43)	0.024 (21.59)	96
75	0.1	0.256 (21.48)	0.028 (21.80)	81
50	1	0.257 (21.52)	0.035 (21.63)	54
25	10	0.260 (21.96)	0.045 (21.32)	32

Ref: G. Barone-Adesi and R. E. Whaley, "Efficient Analytic Approximation of American Option Values," The Journal of Finance, Vol. XLII, No. 2, June 1987.

Variance Reduction: American Options



Numerical Results IV: Low-Biased Solution VS High-Biased Solution

Use our control martingale. (Rogers' approach is not easy to generalized to SV models.)

$1/\varepsilon$	δ	Std_{low}^{PriCV}	Std_{high}^{Dul}
100	0.01	0.0240 (21.59)	0.0239 (22.29)
75	0.1	0.0286 (21.80)	0.0271 (22.33)
50	1	0.0350 (21.63)	0.0334 (22.37)
25	10	0.0453 (21.32)	0.0433 (22.29)

Conclusion

- **Martingale** control variate method is very general for option pricing problems. The control is related to the accumulative value of **delta-hedging** portfolios.
- This variance analysis technique can also be applied to characterize the **error bound analysis** under randomized **Quasi-MC** methods.
- some future works on importance sampling and the use of statistical estimation..etc.

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